Characterizing the Relationship between Carbon Dioxide Emissions and Vehicle Operating Modes on Roundabouts - A Pilot Test in a Single Lane Entry Roundabout

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Abstract
Roundabouts were initially installed to improve traffic flow and safety. However, the reduction may be not only limited to the idling duration. This research attempts to characterize the relationship between CO₂ emissions and vehicle's operating modes on a roundabout. An on-board emission pilot test was conducted on a one-lane-entry roundabout with four legs between Westcott Street and Washington Avenue in Houston, Texas, during peak and nonpeak hours of two consecutive weekdays. The test vehicle was a two-year old gasoline vehicle, which was equipped with a Portable Emission Measurements System (PEMS) to detect real-time exhaust emission rates from the tailpipe and estimate fuel consumption rates. A Global Positioning System (GPS) with magnetic force was placed on the roof of the vehicle to record vehicle’s dynamic geolocation, while an On-board diagnostic (OBD) II port was connected to the test vehicle collected real-time vehicle operation information, such as speeds. Results showed that 35 km/h approaching speed could minimize the CO₂ emissions. Hard acceleration can lead to a spike in the CO₂ emissions, while speeding by frequent small acceleration is beneficial to control the emissions. The longer route within the roundabout is in favor of fewer CO₂ emissions. The vsp between 0 and 9 kw/ton and speed between 1.6 km/h and 40.2 km/h (1-25 mph) are identified as the typical feature of the vehicle operations on the roundabout.

Keywords: Roundabout; Greenhouse gas emissions; Anthropogenic CO₂ emissions; Driver's driving behaviors; Fuel consumption

Introduction
A greenhouse gas is referred to a gas in an atmosphere that absorbs and emits radiation within the thermal infrared range [1]. Atmospheric carbon dioxide (CO₂) is one of the greenhouse gases. Most of today's CO₂ molecules will be removed from atmosphere by mixing into the ocean, photosynthesis, and other processes [2] in few decades, whereas the removal of the CO₂ from the geological reservoirs, approximately 20%, may take many thousands of years [3-5]. In recent decades, anthropogenic CO₂ emissions to the atmosphere have been growing rapidly. A total of 6,870 million metric tons of CO₂ equivalent greenhouse gases were emitted in 2014 in the United States (US) and 81% of the total is CO₂. The transportation sector is directly responsible for 26% of the anthropogenic CO₂ emissions [6] and the transportation related emissions have been increasing by 45% in last two decades [7]. Particularly, burning fossil fuel by passenger cars accounts for 34% of the CO₂ emissions from the transportation sector [8].

Many strategies have been implemented to reduce the CO₂ emissions and improve fuel economy in vehicles, by vehicle designs, biofuels, road design, intelligent transportation system [9-14]. Regarding the road design, in recent decades, it has been proven that a modern roundabout is able to minimize the CO₂ emissions by reducing vehicles’ idling duration [15]. The modern roundabout is a circular intersection or junction, in which vehicle traffic flows almost continuously in one direction around a central island [16]. Drivers yield at entry to traffic flow within the roundabout. The roundabout was initially proposed to improve mobility and safety at intersections and demonstrated that it outperforms STOP sign controls and signalized intersection controls [17].

Additionally, Mandavilli [18] compared CO₂ emissions before and after installing the modern roundabout and found that it enables vehicles to reduce vehicle idling duration, thereby improving traffic flow as well as diminishing CO₂ emissions and fuel consumption. Another study by Hesh [19] estimated the CO₂ emissions from vehicles on a roundabout and reported that compared with a signalized intersection, the modern roundabout can significantly reduce CO₂ emissions and fuel consumption by 21.31% and 26.92%, respectively. This study supports that the CO₂ emission reduction could be achieved by minimizing stopped delay time. It seems that shortening the idling duration is determinative for the CO₂ emission reduction. However, a number of emission study results demonstrated that the CO₂ emission is highly associated with vehicles' operations [20,21].

Nevertheless, a vehicles' operating pattern on roundabouts has been not yet explored and its association with the CO₂ emissions is rarely investigated. These are essential for decision makers to design and install a modern roundabout that can maximize its benefits, in terms of the reduction in CO₂ emissions, safety and mobility. This research attempts to characterize the relationship between CO₂ emissions and vehicle's operating modes on a typical modern roundabout by an on-board emission pilot test.

Methods

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Received March 28, 2017; Accepted April 03, 2017; Published April 09, 2017

Citation: Liu S, Li Q, Qiao F, Du J, Yu L (2017) Characterizing the Relationship between Carbon Dioxide Emissions and Vehicle Operating Modes on Roundabouts -A Pilot Test in a Single Lane Entry Roundabout. Environ Pollut Climate Change 1: 120.

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Vehicle operating mode on roundabout

In the most widely used emission model, Motor Vehicle Emission Simulator (MOVES), vehicle’s operations are classified into 23 operating mode bins to estimate exhaust emissions. Each bin is identified by vehicle’s instant driving speed (\(v\)), acceleration rates (\(a\)), and vehicle specific power (\(vsp\)). Table 1 shows the specific definition of the MOVES operating mode characteristics.

The \(vsp\) is the instantaneous power demand of a vehicle for motion divided by its mass. The power demand is subject to aerodynamic drag, acceleration, rolling resistance, grade, and the mass of the vehicle [22,23]. The \(vsp\) is a function of multiple factors, such as driving speed, acceleration rate, and road grade. As the test vehicle only executes one task of driving and other power-consumed devices are off, the power demand is mainly for vehicle’s motion purpose. In this case, the \(vsp\) is a function of driving speed, acceleration rates, and grades. The \(vsp\) estimation is expressed by Equation (1)

\[
vsp = v^* (1.1 * a + 9.81 * grade (%) + 0.132) + 0.000302 * v^3
\]

1. Where:
2. \(v\): is vehicle speed (assuming no headwind) in m/s
3. \(a\): is vehicle acceleration in m/s²
4. \(grade\): is acceleration due to gravity

As the test site is on a plain, the grade was assumed as zero in Equation (1). Therefore, the \(vsp\) estimation is simplified as Equation (2) [8].

\[
vsp = v^* (1.1 * a + 0.132) + 0.000302 * v^3
\]

Taking CO₂ emissions as an example, Figure 1 shows the distribution of the default average CO₂ emission rates (g/s) on the Operating Mode Bin from a five-year old gasoline passenger car in the MOVES model.

In Figure 1, the lowest CO₂ emission rates are observed in bins 0 and 1 for braking and idling mode. Between bins 11 and 40, there are three waves in the CO₂ emission rates. The wave gradually increases steeper.

For each wave, the CO₂ emission rates increase steadily and then reach the spike in bins 16, 30 and 40. The CO₂ emission rates from the spike drop significantly in the subsequent bin and restart the climb.

On-board emission tests

An on-board emission pilot test was conducted using a Portable Emission Measurement System (PEMS). A typical one-lane entry roundabout located at the intersection between Westcott Street and Washington Ave in Houston, Texas, was chosen for the test site. Figure 2 shows the horizontal view of the roundabout.

As Figure 2 shown, approaching vehicles to the roundabout are controlled by a YIELD sign at the entrance point indicated by a dash line. To avoid the interference of individual driving behaviors, one licensed test driver was recruited to drive through the roundabout towards three exits for multiple times during peak and nonpeak hours of two weekdays. For each round, the test driver drove through three segments, including approaching lane, within the roundabout, and leaving lane. Regarding the 3 segments and 3 exits, a total of 9 scenarios were designed and listed in Table 2.

The test routes for the six scenarios are illustrated in Figure 3. In Figure 3, the test driver departed from “Start” point on the approaching lane of Arnot St. Southeast-bound, about 200 m to the roundabout, for all scenarios. At the yield line, the driver yielded all traffic flow within the roundabout before merging. For S1-S3, the test driver drove towards the first exit from the right direction; Westcott St. Southeast bound and ended at 200 m away the roundabout. The length of the on-roundabout was about 20 m for the first exit. Likewise, the end points for S4-S9 are located at about 200 m away the roundabout on individual leaving lane, namely Washington Ave Eastbound for the 2nd exit and Arnot St. Southeast-bound for the 3rd exit in the afternoon.

<table>
<thead>
<tr>
<th>Operating Mode ID</th>
<th>Operating Mode Description</th>
<th>Vehicle Specific Power, (vsp) (kW/ton)</th>
<th>Vehicle Speed, (v) (km/h)</th>
<th>Vehicle Acceleration, (a) (m/s²)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Braking</td>
<td>-</td>
<td>1.6 ≤ (v) ≤ 1.6</td>
<td>((a_0 ≤ -0.9)) or ((a_0 ≤ -0.4 \text{ and } a_{t-1} ≤ -0.4 \text{ and } a_{t-2} ≤ -0.4))</td>
</tr>
<tr>
<td>1</td>
<td>Idling</td>
<td>VSP&lt;0</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
</tr>
<tr>
<td>11</td>
<td>Low Speed Coasting</td>
<td>VSP&lt;0</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
</tr>
<tr>
<td>12</td>
<td>Cruise/Acceleration</td>
<td>0 ≤ VSP&lt;3</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
</tr>
<tr>
<td>13</td>
<td>Cruise/Acceleration</td>
<td>3 ≤ VSP&lt;6</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
</tr>
<tr>
<td>14</td>
<td>Cruise/Acceleration</td>
<td>6 ≤ VSP&lt;9</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
</tr>
<tr>
<td>15</td>
<td>Cruise/Acceleration</td>
<td>9 ≤ VSP&lt;12</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
</tr>
<tr>
<td>16</td>
<td>Cruise/Acceleration</td>
<td>12 ≤ VSP</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
<td>1.6 ≤ (v) ≤ 40.2</td>
</tr>
<tr>
<td>21</td>
<td>Moderate Speed Coasting</td>
<td>VSP&lt;0</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
</tr>
<tr>
<td>22</td>
<td>Cruise/Acceleration</td>
<td>0 ≤ VSP&lt;3</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
</tr>
<tr>
<td>23</td>
<td>Cruise/Acceleration</td>
<td>3 ≤ VSP&lt;6</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
</tr>
<tr>
<td>24</td>
<td>Cruise/Acceleration</td>
<td>6 ≤ VSP&lt;9</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
</tr>
<tr>
<td>25</td>
<td>Cruise/Acceleration</td>
<td>9 ≤ VSP&lt;12</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
</tr>
<tr>
<td>27</td>
<td>Cruise/Acceleration</td>
<td>12 ≤ VSP&lt;18</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
</tr>
<tr>
<td>28</td>
<td>Cruise/Acceleration</td>
<td>18 ≤ VSP&lt;24</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
</tr>
<tr>
<td>29</td>
<td>Cruise/Acceleration</td>
<td>24 ≤ VSP&lt;30</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
</tr>
<tr>
<td>30</td>
<td>Cruise/Acceleration</td>
<td>30 ≤ VSP</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
<td>40.2 ≤ (v) ≤ 80.4</td>
</tr>
<tr>
<td>33</td>
<td>Cruise/Acceleration</td>
<td>VSP&lt;6</td>
<td>80.4 ≤ (v)</td>
<td>80.4 ≤ (v)</td>
</tr>
<tr>
<td>35</td>
<td>Cruise/Acceleration</td>
<td>6 ≤ VSP&lt;12</td>
<td>80.4 ≤ (v)</td>
<td>80.4 ≤ (v)</td>
</tr>
<tr>
<td>37</td>
<td>Cruise/Acceleration</td>
<td>12 ≤ VSP&lt;18</td>
<td>80.4 ≤ (v)</td>
<td>80.4 ≤ (v)</td>
</tr>
<tr>
<td>38</td>
<td>Cruise/Acceleration</td>
<td>18 ≤ VSP&lt;24</td>
<td>80.4 ≤ (v)</td>
<td>80.4 ≤ (v)</td>
</tr>
<tr>
<td>39</td>
<td>Cruise/Acceleration</td>
<td>24 ≤ VSP&lt;30</td>
<td>80.4 ≤ (v)</td>
<td>80.4 ≤ (v)</td>
</tr>
<tr>
<td>40</td>
<td>Cruise/Acceleration</td>
<td>30 ≤ VSP</td>
<td>80.4 ≤ (v)</td>
<td>80.4 ≤ (v)</td>
</tr>
</tbody>
</table>

Table 1: Definition of MOVES operating mode characteristics (US EPA [25]).
bound for the 3rd exit. The on-roundabout lengths are approximately 60 m and 117 m for the 2nd and 3rd exit, respectively.

Table 3 shows the test vehicle’s specification, which information was input to the PEMS that was placed at the backseat of the test vehicle. The screenshots of the test vehicle and the in-vehicle PEMS are shown in Figure 4.

While the PEMS was connected to the On-Board Diagnostics (OBD) port of the test vehicle for real-time vehicle operation information, such speed, a global positioning system (GPS) device with magnetic force was placed on the roof of the vehicle to record vehicle’s real-time geo-location, including longitude, altitude, and latitude. Vehicle’ acceleration rates were calculated based on the speed collected from the OBD. Meanwhile, the exhaust from the tailpipe was sucked to the gas condenser then to the gas analyzer of the PEMS for real-time emission rates of a specific emission. The real-detected CO₂ emissions by the PEMS were monitored for this study.

Data process

The PEMS collected data includes second-by-second CO₂ emission rate in g/s, driving speeds (v) in m/s, Geo-location, and fuel consumption rate in g/s, at a time domain. The distribution of the CO₂ emission pattern and the variability of samples indicated by interquartile range (IQR), were visualized by a boxplot. The time domain emission rates and Fuel Consumption (FC) on the routes were interpolated to meter-by-meter distance domain for the comparison of the emissions on each segment.

Meanwhile, the driving speeds were calculated to acceleration rates. The vsp was further estimated using the speed and acceleration rates.

Results and Discussion

Distribution of CO₂ emissions on segments

Figure 5 illustrates CO₂ emission distribution on the three segments while driving towards the three exits.
The CO₂ emissions on the roundabout range from 0.1 g/s to 0.7 g/s. Apparently, the CO₂ emissions on the approaching lane for the 2nd and 3rd exit are much denser at the lowest level, indicating by smaller IQR (shorter box). Meanwhile, there are more outliers denoted by the red crosses on their boxes. Besides, as this is a one-lane entry roundabout, the test vehicle's operation on the approaching lane shall not be subject to the subsequent exit selection. However, the CO₂ emissions obviously vary with each test. It is worth noting that the driving tasks on the approaching lane are more complex than on other lanes. The driving task could include deceleration, possible idling for an acceptable gap, timely acceleration for merging into the traffic flow, which highly depends on traffic flow in the roundabout. Therefore, the difference in the CO₂ emission distribution on the approaching lane may be attributed to the complex vehicle operation. The dense samples distribute at the bottom implies that the test vehicle more often idle at the dash line for yielding vehicle flow. The median levels (red line in the box) of the CO₂ emissions on the approaching lane are relatively close to each other and lower than those in other scenarios.

Within the roundabout, speeding up and maintaining a driving speed as the flow within the roundabout could be the main driving task. While the higher variability of the CO₂ emission rates is observed in the scenarios for the 1st exit, the higher median level is the ones for the 2nd exit. The difference in the CO₂ emissions among the scenarios for the three exits is the driving speeds and the length of the test routes within the roundabout. The test route for the 3rd exit is the longest with 117 m and its median level is the lowest, whereas the highest median level is found on the second-longest test route towards the 2nd exit. This excludes the impacts of the route length on the CO₂ emissions.

On the leaving lane, rare emission samples are observed at the bottom, which means the test vehicle did not idle at the exit. Therefore, maintaining the driving speed is the main driving task. The CO₂ emission distribution within and leaving the roundabout reflects the difference in the maintained traffic flow speeds.

**CO₂ emission pattern on a roundabout**

Figure 6 shows the CO₂ emission and FC profiles while driving through the roundabout towards the three exits. The yield line in Figure 3 was set as zero distance on x-axis. The signs “-” and “+” in represent the direction of approaching and leaving the yield line, respectively, while the shadows indicate the variation area of the CO₂ emission and FC factors. The purple dash lines separate the route into three segments. The negative distance is on the approaching lane, while the on-roundabout lane lies in between the two purple dash lines. The leaving lane is right after the on-roundabout lane on positive distance.

As a whole, the trend lines CO₂ and FC as well as their variations
are almost overlapped throughout the profiles. As all carbon-based fuel in a vehicle is intentionally converted to CO$_2$ to release energy, the overlapping profiles imply that there is no visible difference in the test vehicle's fuel efficiency among the scenarios. Besides, the overall emission factors on the longer test route towards the 3rd exit are lower than those on the shorter routes towards the 1st and the 2nd exits.

There is a common trend on the approaching lane before entering the roundabout. The CO$_2$ decreases gradually from -100 m away to the roundabout, and reaches the lowest emission point at about -60 m, then spikes to another higher level before the yield line (0 m on x-axis). This pattern is in accord with the driving tasks with the sequence of deceleration, idle, and then acceleration, on the approaching lane. Besides, before the yield line, there was only one spike on the approaching lane between -60 m and 0 m for the 2nd and 3rd exits, while there were two spikes for the 1st exit. The exclusive CO$_2$ emission spike for the 2nd and 3rd exit might explain the outliers in Figure 5.

Within the roundabout, the emission variation for the 1st exit was apparently larger than for other exits, which was also reflected by the longer IQR in Figure 5. For the 2nd and 3rd exits, the overall CO$_2$ emissions are stable at a certain level within the roundabout. Before leaving the roundabout, another spike presented and then gradually declined afterward.

**Vehicle operating patterns on a roundabout**

Figure 7 demonstrates the speed and acceleration profiles while driving through the roundabout.

On the approaching lane, the acceleration profiles in green fluctuate frequently and hardly than those on other segments. A gradual deceleration was operated before -60 m and subsequently two harder accelerations at about -20 m and around the yield line to the roundabout, respectively. The corresponding speed in red for the 2nd and 3rd exits declined sharply, whereas the speed for the 1st exit performed differently. For the 1st exit, about 28 km/h was maintained and then it increased for a while and sharply decreased before entering the roundabout. It was noticed that the starting speed from -100 m for the three exits were not consistent. The starting speeds were 28 km/h, 35 km/h, and 32 km/h, for the 1st, 2nd and 3rd exits, respectively. The lower starting speed for the 1st exit enabled the speeding to react gently preparing the upcoming yield control. Recalling the lower emission distribution on the approaching lane for the 2nd and 3rd exits in Figure 5, the approaching speed of 35 km/h was in favor of emission reduction and fuel consumption efficiency. Besides, instead of two spikes, the two hard acceleration actions for the 1st exit brought about higher variation for the shorter duration and travel distance between them before merging the traffic flow. For the 2nd and 3rd exits, the harder accelerations would be responsible for the emission spikes mentioned above.

Within the roundabout, frequent small acceleration actions were operated for the 2nd and 3rd exits, which could control the emission at the certain level mentioned above. However, it seems that the emission variation for the 1st exit does not react in this way. This may be due to the shorter route length and the flow speed. The red speed lines in Figure 7 performed a gradual rise for the three exits. At the exit point, the common speed was 30 km/h, which indicates the flow speed within the roundabout. Variant maneuvers of speeding up from 22 km/h to 30 km/h at the shorter distance with 20 m, for the 1st exit could account for its longer IQR or higher variation.
spent on the braking mode on the approaching lane for the three exits, and no idling was operated. Within and leaving the roundabout, rare braking and idling were operated.

The speed continued to increase on the leaving lane, while the corresponding acceleration lines kept stable. On the other hand, the CO₂ emissions in Figure 6 overall fluctuated within a certain level. In other words, higher driving speed could be accompanied with lower CO₂ emissions for higher fuel efficiency and the CO₂ emissions were sensitive to acceleration rates, rather than the speed.

Features of operating modes on roundabout

Figure 8 shows the distribution of the test vehicle's operation modes while driving through the roundabout towards three exits. As the test vehicle's operation modes distributed from bins 0 to 25, the limit of the x-axis was set to bin 25 in Figure 8. Based on Figure 1, the lowest CO₂ emission rates were observed in bin 0 and 1 represented biking and idling modes. Figure 8 shows that about 20-28% of operating time were spent on the braking mode on the approaching lane for the three exits, and no idling was operated. Within and leaving the roundabout, rare braking and idling were operated.

Generally speaking, most operating information fell into the lower CO₂ emission wave between bins 11 and 16. In particular, more than 90% of driving time the test vehicle was operated at a lower speed (<40.2 km/h) and a lower vsp (<9 kw/ton), within the roundabout for the three exits. Specifically, the test vehicle was mostly under the operating modes between bins 12 and 14, ranging from 41% for the approaching lane towards the 2nd and 3rd exits (Figures 8d and 8g); to 100% within the roundabout towards the 2nd exit (Figure 8e).

Only a small portion of driving time was spent on the operating modes between bins 21 and 24. However, Figure 1 demonstrated that the CO₂
emission rates in such bins were almost equal to the emission levels in bins 12 to 14. Therefore, the overall emission levels on the roundabout were comparable to the first CO₂ emission wave in Figure 1.

In terms of exit selection, Figure 9 illustrates the time distribution to the Operating Mode IDs. Obviously, a greatest proportion of the driving time was occupied by the bins between 12 and 14, with 59%, 74% and 73%, for the three exits, respectively, followed by bins 0 and 1 for the braking and idling modes, and bin 11 for low speed coasting. In other words, vsp between 0 and 9 kw/ton and speed between 1.6 km/h and 40.2 km/h (1-25 mph) were the typical feature of the vehicle operations on the roundabout.

Conclusion

An on-road pilot emission test was conducted in a typical one-lane entry roundabout in Houston, Texas, using PEMS. Real-time emission rates, fuel consumption rates, and vehicle's operation information were collected while driving through the roundabout towards different exits. The test vehicle's CO₂ emissions were compared among 9 scenarios on three segments, including an approaching lane, within the roundabout, and the exiting lanes linked with the roundabout (leaving lanes). It was found that usually one deceleration, two acceleration actions are required before merging into the traffic flow in the roundabout. 35 km/h approaching speed could minimize the CO₂ emissions on lanes. Hard acceleration can lead to a spike in the CO₂ emissions, while frequent small acceleration for gradual speeding is beneficial to control the emissions within a certain level. The higher CO₂ emission and variations are observed at the shorter route and the CO₂ emissions are sensitive to acceleration. The overall emission level on the roundabout are comparable to the lower CO₂ emission level shown in Figure 1. Operating Mode Bins 12 to 14 was identified as the typical feature of the vehicle operation on the roundabout.

Acknowledgement

The authors acknowledge that this research is supported in part by the National Science Foundation (NSF) under grants #1137732. The opinions, findings, and conclusions or recommendations expressed in this material are those of the author(s) and do not necessarily reflect the views of the funding agencies.

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