Modelling of Blood and Dialysate Flow in Hollow-Fiber Hemodialyzers

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Abstract

One of the problems that mostly arises in kidney diseases, is abnormal reduction of fluid removal in the body, which increases the level of acids and increase normal range of molecules such as urea, glucose, creatinine, beta 2 micro globulin and complement factor D. Due to the availability of technologies to produce membranes and fibers, it is possible to remove these toxins by producing membrane sets, such as dialysis. The heart of a dialysis is dialyzer that filters toxins and extra water of the body through its hollow membranes. In this regard, a model is needed to investigate and optimize process of toxin clearance, in order to reduce manufacturing costs and increase efficiency of dialysis. Since process parameters and dialysis structure determines elimination level and also the stay of useful molecules in blood, manufacturing design is of great importance. In this paper, a two-dimensional model of speed, pressure and flow concentration was prepared for both blood and dialysate phase, and discretized using finite difference method. Here, the simulation was carried out using MATLAB software. In the present work we try to build a 2-D model of blood and dialysate flows as a platform to study dialyzer performance in the future.

Keywords: Dialysis; Simulation; Modelling; Membrane fibers

Introduction

Hemodialysis is essentially a filter for blood flow, which cleans blood toxins of patients with artificial kidney. This blood filtering system is capable to be mounted on a patients body in hospitals and even at home, while it doesnt need special care during the filtering [1]. In fact, the process of dialysis plays the role of a kidney and is of use for kidney patients. During hemodialysis process, the patient's blood drives to very thin porous fibers [2]. In the case of homogeneous membranes for dialysis, the literature witnesses considerable and valuable researches. Such dialysis membranes are generally made using cellulosic materials, in which a homogeneous porous structure is present from the membrane entry to the exit. The surface of the membranes are not very biocompatible with blood flow because of the exposure in the hydroxyl groups. That is why dialysis membranes are generally made of synthesized materials such as poly ary, ether sulfate, poliyamide, polycarbonate and polycracylamide. This type of membrane, known as asymmetric structure, is less active compared to cellulose membranes, which means that its hole shapes gradually change from the entry to the exit of membrane surface. Although synthesized membranes are mostly in the form of high flux, they can be made in both high and low flux forms [3]. The majority of hemodialysis membranes are designed for toxic clearance and prevention of protein penetration, and thus, the design should prevent back filtration [4]. Although, experimental studies conducted so far have investigated what is the effect of blood or dialysate flow rate on the elimination of toxins [5], they have not examined membrane structure, and also have usually been limited to the removal of urea. One of the main challenges ahead of clinicians is the duration of dialysis procedures in case of penetration of important molecules, such as albumin material. Most laboratory studies about dialysis are commercially available and in fact provide a comparison between different dialyzers [4]. In a dialysis, materials, including sodium, potassium, calcium, magnesium, chloride, bicarbonate and glucose, move to dialysate solution. In the meantime, toxins and excess water will be removed from blood. For maximization of the efficiency, the blood and dialysate flow will be counter-current. This process continues until the concentration of undesirable materials reaches to normal-level. The size of the pores should be small enough to prevent transmission of blood cells, but pass undesirable materials. The purification process usually takes three to five hours and is done two or three times a week [2]. During the operation, blood distributes in the fibers, and excess water and toxins move into the dialysis solution due to pressure and concentration difference with the external environment of the fiber. Figure 1 shows how the dialyzer device installs on the body's patients. Schematics of blood current outside the patient's body by hemodialysis [1] (Figure 1). One of the efforts in this regard is simulating how mass transfers in a porous fiber [6]. In the present model, angle gradient terms are ignored in blood and dialysate flows. paper.

Governing Equations

This paper is focused on the simulation of counter-current blood and dialysate solution flows. The transfer of the aforementioned materials in membrane shell is similar to heat transfer in shell and tube converters [3]. In the present model, it is assumed that laminar flow conditions are perfectly preserved. To investigate different structural and operational parameters, the authors studied filter F60 (Fresenius, Germany), that its structural and morphological characteristics are available in references [1].

Differential equations of concentration and velocity of blood flow

In dialysis input flow due to current contact with the membrane's inner walls, the velocity distribution will be developed that is considered as an input boundary condition for velocity:

\[ U_z(r) = \frac{2qb}{N^2_h} \left( r^2_b - r^2 \right) \text{ at } z = 0 \]  

(1)

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Eq. 1 provides the velocity distribution of blood at the entrance of a fiber. Here, $q_b$ is the input flow rate of blood, which determines a velocity distribution from zero at radius $r_b$ to fiber axis. It is assumed that there are no sliding conditions in the wall and there is fiber symmetry axis at $r=0$ [7]. At totally developed flow conditions, Navier Stokes equations and continuity equation are governed in accordance with the following process, by the assumption that the dialysate and blood flow are Newtonian and incompressible [7].

Here the parameter $q_d$ indicates the flow rate at the dialysate entrance and the ratio $k((r_b/r_d))$ and $L_r$ are the structural characteristics of the hollow fiber [7].

In these equations, $D$ refers to the diffusion coefficient of solutes in the same solutions and a non-porous medium and is a function of solute’s molecular weight. $r$ and $r_p$ also represent the solute and pore radius respectively [8].

The velocity distribution of the input flow in the dialysate solution is considered accordance with equation (9).

Here the parameter $q_d$ indicates the flow rate at the dialysate entrance and the ratio $k((r_b/r_d))$ and $L_r$ are the structural characteristics of the hollow fiber [7].

**Boundary conditions**

In this work, initial and boundary conditions determine the velocity and concentration distribution of the profile. The following are mentioned as the initial and boundary conditions that in papers are totally common. Due to the symmetry of fiber, let: [7]

**Influx and outflux boundary conditions are in accordance with the equation (15) [7] for the concentration equation.**
Numerical Solution

In this paper, the numerical solution was provided using finite difference method. All differential equations were discrete in the form of a finite difference. For a discrete of the first and second order derivatives, central difference estimate was used in accordance with the following relationships.

\[
\frac{\partial^2 U}{\partial x^2} = \frac{U_{i,j+1}^{n+1} - 2U_{i,j}^{n+1} + U_{i,j-1}^{n+1}}{\Delta x^2} \quad \frac{\partial^2 U}{\partial y^2} = \frac{U_{i+1,j}^{n+1} - 2U_{i,j}^{n+1} + U_{i-1,j}^{n+1}}{\Delta y^2}
\]  \hspace{1cm} (15)

\[
\frac{\partial C}{\partial x} = \frac{C_{S,i,j}^{n+1} - C_{S,i,j}^{n}}{2\Delta x}, \quad \frac{\partial C}{\partial y} = \frac{C_{S,i,j}^{n+1} - C_{S,i,j}^{n}}{2\Delta y}
\]  \hspace{1cm} (16)

\[
\frac{\partial C_s}{\partial t} = \frac{C_{S,i,j}^{n+1} - C_{S,i,j}^{n}}{\Delta t}
\]  \hspace{1cm} (17)

In order to discretize the time derivative, the following formulae were utilized.

Results and Discussion

Due to the boundary conditions, it is clear that the maximum velocity will be at the axis of fiber, while it decreases to zero on the surface of the membrane’s wall. It should be noted that various parameters affect velocity distribution, including level of the flux in and out of the membrane and solution pressure (Figure 2).

From Figure 3, it could be seen that the total flux of blood out of the membrane was in some parts positive and in some places negative. The parameter that determines the positive and negative in and out flux (mainly water and dialysate solution) is membrane input and output pressure for both blood and dialysate phase. Also by careful observation at shells, it is characterized that in the maximum and minimum of the radial velocity was achieved at certain radial points.

According to Figure 4, pressure distribution is descending along the flow direction. Based on the counter currents, the maximum pressure of the dialysis (the input of the dialysate solution) was associated with the lowest pressure in blood output, and vice versa. As it was explained, this pressure difference leads to fluid flow force.

Figure 5 shows how the urea concentration changes with axial and radial dimensions in both blood and dialysate compartments. The concentration profiles show non-linear change of urea concentration along both axial and radial dimensions. Figure 6 shows how urea concentration varies within he membrane thickness. Figure 6 shows how urea concentration varies within he membrane thickness.

Conclusion

The model developed in this paper can be used to predict solute concentration, pressure and velocity profiles as a function of time and dialyzer structural dimensions. Model predictions have shown that solute concentration in the radial direction which is normally assumed to be uniform in other studies, change nonlinearly. In addition, existence of radial velocity plays an important role in convection transport of larger molecules.

Conflict of Interest

The authors declare that they have no conflict of interest.
References